

Multi-Valued Logic

- VHDL allows users to extend the language by defining their own data types
- Early on, users recognized that the BIT data type was insufficient for digital simulation
 - BIT can only have values of '1' or '0'
 - Digital systems require other conditions such as 'Z' (tri-state), 'X' (unknown), weak/strong drivers, etc.
- Companies began writing VHDL models that used proprietary data types that added support for these logic values
 - Each company defined their own data types
 - Models were not interoperable because they used these custom data types

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IEEE Standard Multivalued Logic System (1164)

- An IEEE standards body created the *std_logic_1164* standard to support multivalued logic in VHDL
- A *std_logic* data type has the following values:
 - 'U' uninitialized (leftmost literal, default initial value)
 - 'X' forcing unknown
 - '0' forcing 0
 - '1' forcing 1
 - 'Z' high impedance
 - 'W' weak unknown
 - 'L' weak 0 (pulldown)
 - 'H' weak 1 (pullup)
 - '-' don't care (used for synthesis only)

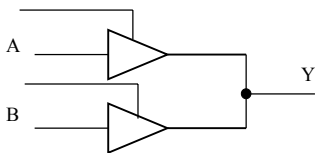
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Resolved Data Types

- *std_logic* is known as a *resolved* data type in VHDL
- A *resolved* data type allows more than one driver for a signal
- Necessary for modeling things like tri-state drivers, pullup/pulldown networks.



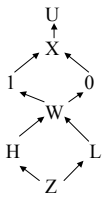
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The Resolution Function

- The resolution function determines the final value of a signal in the case of multiple drivers
- The diagram below is a graphical representation of the resolution function for *std_logic*.



Increasing strength
 'Z' is weakest, 'U' is strongest.

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Unresolved Types

Cannot have multiple drivers for types that do not have a resolution function. A BIT type is an unresolved type.

```

signal ta,tb : bit;
begin
  ta <= transport '1' after 2 ns; -- 'ta' only has one driver
  tb <= transport '1' after 3 ns; -- 'tb' has multiple drivers

  p1:process
  begin
    tb <= transport '0' after 5 ns;
    wait;
  end process p1;
-- The following compilation error is generated
--##### exam2/driverbad.vhd(27):      tb <= transport
--ERROR: exam2/driverbad.vhd(27): Nonresolved signal tb
line 24).
--##### exam2/driverbad.vhd(32): end;
--ERROR: exam2/driverbad.vhd(32): VHDL Compiler exiting
end;
    
```

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Driver Resolution: Example #1

```

signal tb : std_logic;
begin

  -- 'tb' has multiple drivers
  tb <= transport '1' after 3 ns;  -- DRV0

  p1:process
  begin
    tb <= transport 'L' after 5 ns; -- DRV1
    wait;
  end process p1;

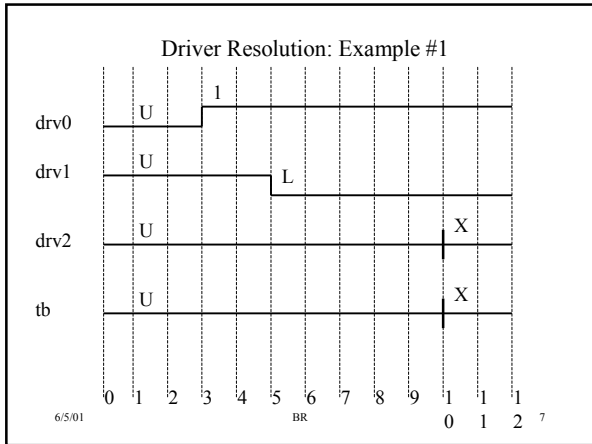
  tb <= transport 'X' after 10 ns; -- DRV 2
end;
    
```

What does the waveform of signal *tb* look like?

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Driver Resolution: Example #2

```

signal tc : std_logic := 'Z';
begin
  -- 'tc' has multiple drivers
  tc <= transport '1' after 3 ns; -- DRV0

  p1:process
  begin
    tc <= transport 'L' after 5 ns; -- DRV1
    wait;
  end process p1;

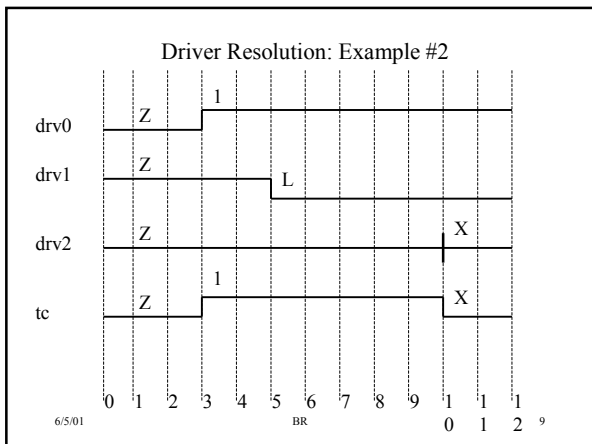
  tc <= transport 'X' after 10 ns; -- DRV 2
end;

```

Only difference from previous example is *tc* has an initial value of 'Z'

What does the waveform of signal *tc* look like?

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Driver Resolution: Example #3

```

signal td : std_logic := 'Z';
begin

  -- emulate a pullup resistor using 'H' drive
  td <= 'H';    -- DRV0
  -- DRV1
  td <= transport '0' after 2 ns, 'Z' after 4 ns;
  -- DRV2
  td <= transport '0' after 5 ns, 'Z' after 7 ns;
  -- DRV3
  td <= transport '0' after 6 ns, 'Z' after 10 ns;
end;

```

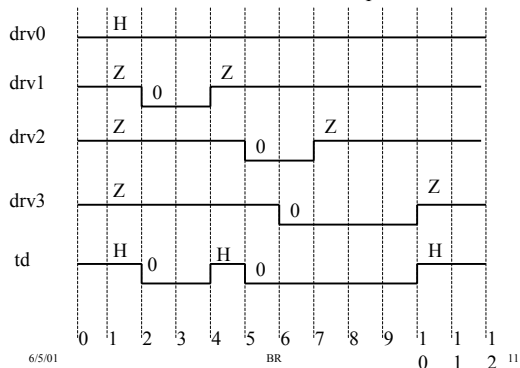
What does the waveform of signal *td* look like?

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Driver Resolution: Example #3



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0 1 2 3 4 5 6 7 8 9 10 11

Details on 1164

- Look at the *std_logic_1164.vhd* file attached to the class WWW page
- *std_ulogic* is the base type defined in the 1164 standard
 - This is an unresolved type
 - signals of type *std_ulogic* cannot have multiple drivers
- *std_logic* is the resolved subtype of *std_ulogic*
 - a resolved type is always a subtype of another unresolved type

```

type std_ulogic is ('U', 'X', '0', '1', 'Z',
  'W', 'L', 'H', '-');
subtype std_logic is resolved std_ulogic;

```

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std_logic vs *std_ulogic*

- *std_logic* is subtype of *std_ulogic*
- Subtypes can be used in place of the type from which it was derived, without needing an explicit conversion function
- *std_ulogic* signals can be assigned to *std_logic* signals, and vice versa
- *std_ulogic_vector* and *std_logic_vector* are the array types for *std_ulogic* and *std_logic* respectively
 - *std_logic_vector* is not a subtype of *std_logic_ulogic* and a type conversion function is needed for assignments between signals of these types

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std_logic vs *std_ulogic* (cont.)

- You should use *std_ulogic* and *std_ulogic_vector* for signals that only require one driver
 - accidental connections between signals that should only have one driver can be detected by the compiler

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1164 Resolution Table

```
TYPE stdlogic_table IS ARRAY(std_ulogic, std_ulogic) OF std_ulogic;
CONSTANT resolution_table : stdlogic_table := (
-----
-- | U  X  0  1  Z  W  L  H  -  | |
-----
( 'U', 'U', 'U', 'U', 'U', 'U', 'U', 'U', 'U' ), -- | U |
( 'U', 'X', 'X', 'X', 'X', 'X', 'X', 'X', 'X' ), -- | X |
( 'U', '0', '0', '0', '0', '0', '0', '0', '0' ), -- | 0 |
( 'U', 'X', 'X', '1', '1', '1', '1', '1', 'X' ), -- | 1 |
( 'U', 'X', '0', '1', 'Z', 'W', 'L', 'H', 'X' ), -- | Z |
( 'U', 'X', '0', '1', 'W', 'W', 'W', 'W', 'X' ), -- | W |
( 'U', 'X', '0', '1', 'L', 'W', 'L', 'W', 'X' ), -- | L |
( 'U', 'X', '0', '1', 'H', 'W', 'H', 'W', 'X' ), -- | H |
( 'U', 'X', 'X', 'X', 'X', 'X', 'X', 'X', 'X' ) -- | - |
);
```

The resolution function uses the lookup table to resolve types.

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1164 Resolution Function

```
FUNCTION resolved ( s : std_ulogic_vector ) RETURN std_ulogic IS
VARIABLE result : std_ulogic := 'Z'; -- weakest state default
BEGIN
-- the test for a single driver is essential otherwise the
-- loop would return 'X' for a single driver of '-' and that
-- would conflict with the value of a single driver unresolved
-- signal.
IF (s'LENGTH = 1) THEN RETURN s(s'LOW);
ELSE
FOR i IN s'RANGE LOOP
result := resolution_table(result, s(i));
END LOOP;
END IF;
RETURN result;
END resolved;
```

'S' is a list of all driver values for the signal to be resolved.

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What Else is in IEEE 1164?

- Boolean functions (AND, OR, etc)
- Subtypes with restricted members (X01, X01Z, UX01, UX01Z)
 - conversion functions to/from vector types to these types
 - useful in models where you do not want to deal with the full range of types
- Conversion functions to/from BIT, BIT_VECTOR to std_ulogic, std_ulogic_vector
- Misc functions
 - rising_edge, falling_edge, is_X

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