

MathWorks Integrated Design Solution



The MathWorks at a Glance

- Founded in 1984, privately held
- Headquarters in Natick, Massachusetts (near Boston)
- European offices in the UK,
 France, Germany, Switzerland,
 Italy, Spain, and Benelux region
- Over 1000 employees, including ¹/₃ in product development
- More than 500,000 users in 100 countries, on all seven continents!

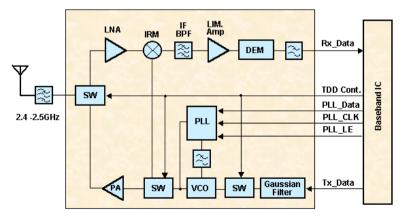


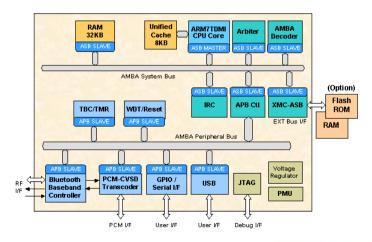




Today's System and IC Design Challenges

- Hardware: RF/Analog, Digital IC, FPGA
- Software: DSP, MAC, Control, Use interface
- Moving partitioning boundaries
 - − Analog ↔ Digital IC ↔ FPGA ↔ DSP S/W ↔ Micro controller S/W
- Implementation specific tools lock your IP into one target type
 - Spice, HDL, ASM , C/C++









Today's Business and Organization Challenges

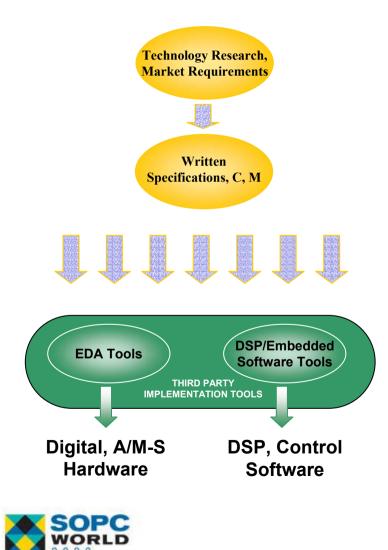
- Time-to-market pressure
 - A few months delay has huge revenue impact
- Team integration
 - Analog/Mixed-Signal,
 Digital hardware, DSP S/W,
 Control S/W teams
 - All speak a different language and communicate via written documents
- Increasing ASIC mask costs







Traditional Flow: Little or No Early Simulation



- Technology research and market requirements
- Systems engineering
- Partition into components create written specifications for teams
- Minimal or no simulation.
 C, M
- Design failure risk high.
 Flaws detected late, during circuit level, RTL or C/ASM code design

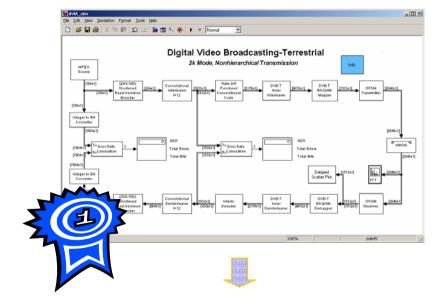
Risk of time-to-market

delays



What if You Could...?

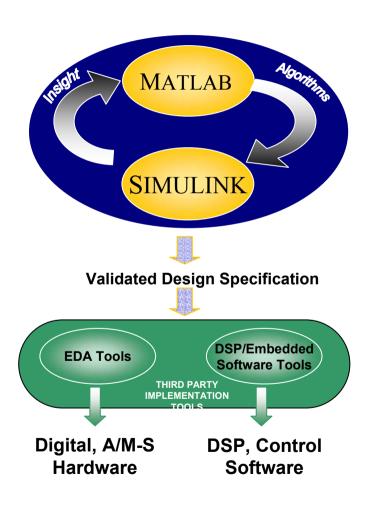
- Build a model of a complete system in minutes or days
- Simulate the behavior of the whole system before starting low-level design work?
 - Analog, digital and control together
 - Test for design flaws early
 - Trade-off architectures and parameter in minutes find best design
- Communicate your ideas and share with other teams?
- Keep your IP in an implementation neutral tool as long as possible?
- Only start development with a validated, fully tested design?







The MathWorks System-Level Solution



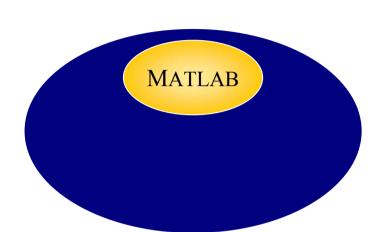
- MATLAB and Simulink
- Before circuit level, RTL or C/ASM code design
- Create a validated reference design

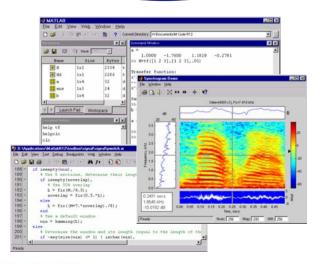
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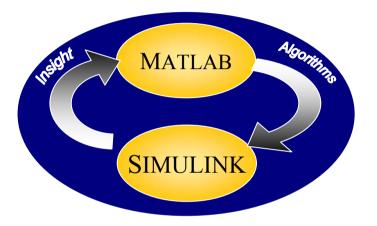


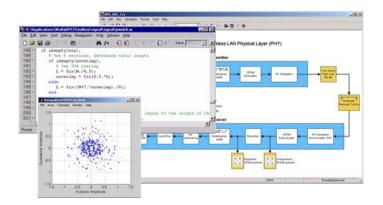
- Research new technology
- Perform mathematical modeling
- Development algorithms
- Acquire, visualize and analyze data





Simulink



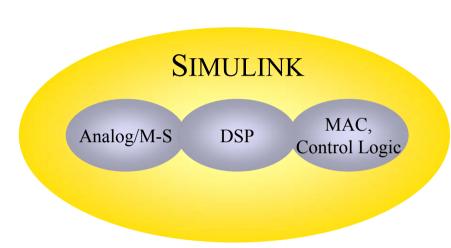




- Graphically design architecture and simulate behavior of whole system. Bit-true cycle accurate.
- From libraries of pre-built blocks
- Import C or MATLAB Code
- Test, optimize, explore parameter and architecture trade-offs

The MathWorks

Model Different Components



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Analog/Mixed-Signal

- PLLs, data converters
- Continuous time, variablestep ODE solvers

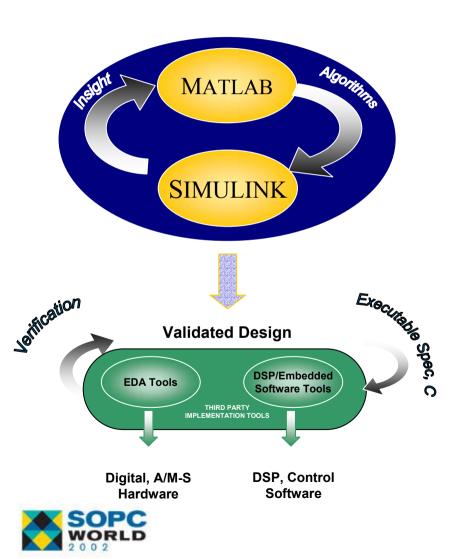
DSP Baseband

- Discrete time, fast framebased processing. Bit-true cycle accurate.
- MAC layer/Data Link Layer
 - Simple protocols, acknowledgement schemes
 - Reactive or event driven state machines
 - With Stateflow



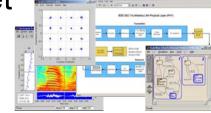


Use a Validated Design



Create validated design

- Use as reference or executable specification to test low-level designs against
- Provide clear specifications
- Detect design flaws early
- Reduce design risk and time-to-market



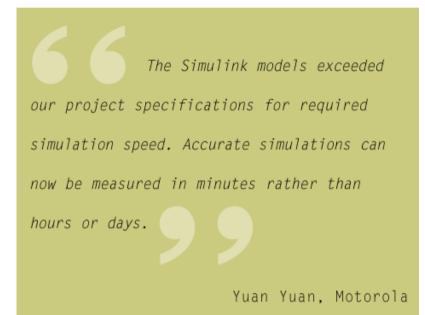


Motorola's Wireless Subscriber Systems Group

Challenge

- Mixed-signal Phase-Locked Loop (PLL) design
- Cycle-to-cycle jitter and loop locking sensitivity
- SPICE/Verilog
- 100 μsecs: 2 hours
- Solution
 - Simulink
 - Faster development time and simulation time
 - 100 μsecs : 2.5 mins
 - Sub-picosecond resolution







PHY Design Case Study: IEEE 802.11b

IEEE Standard Document

- 600 pages (11 + b appendix)
- 4 modes (1, 2, 5.5 and 11Mbps)
- Components
 - Framing and CRC
 - Long/short preamble and sync
 - Modulation and spreading
 - Filtering
 - Channel number selection (1-11)
 - RF subsystems, Tx power, mask, power-on ramp

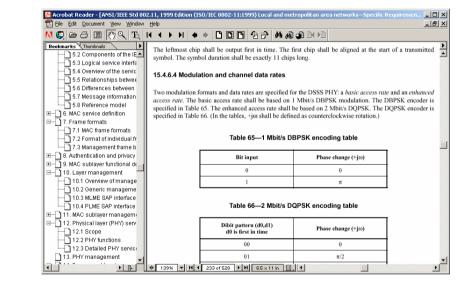






1Mbps Mode

- Modulation
 - DBPSK
- Spread
 - 11 chips Barker sequence per symbol
- Pulse shaping
 - 4/8 samples per chip
 - Root raised cosine
- Channel
 - AWGN



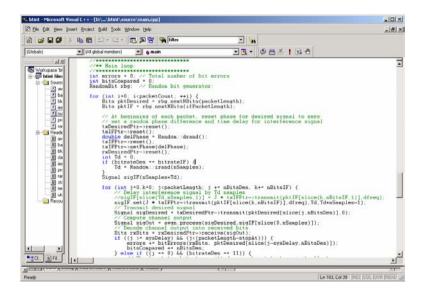






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C/C++





NIST 802.11b and Bluetooth C/C++ Code



- w3.antd.nist.gov/wctg/blu etooth/btint.html
- Bluetooth and 802.11b
- 802.11b
 - Random bits
 - 1 or 11Mbps modulation and spreading
 - Filtering
- Bluetooth
 - Random bits
 - Modulation
 - Filtering





C/C++ Code: 17 Files, 1500-2000 lines

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C/C++ Code: Build, Run, Debug, and Change

Build and run

– Bug: File I/O

Speed

- 7 secs for 100 packets
- Time to create
 - 400 days @ 5
 lines/day
 - 40 days @ 50 lines/day

Removing Bluetooth

 Difficult. Many implicit dependencies
 D: \>b



S/W Demonstration





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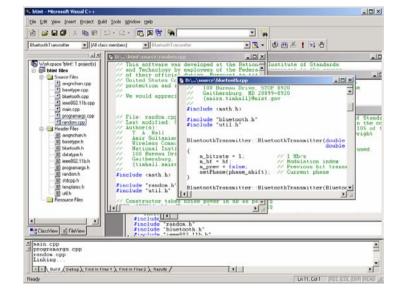
C/C++ Pros and Cons

Pros

- Ubiquitous
- Fast to execute
- Data type options

Cons

- No canned DSP/Comm functions
- Can't visualize signals
- Too low-level, lots housekeeping
- Error prone design entry, implicit interdependencies
- Slow to iterate, debug and make changes











MATLAB

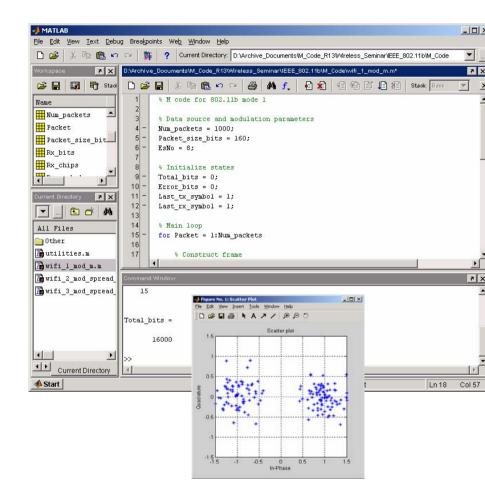
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802.11b: M Code

Using MATLAB

- Generating bits
- Symbols and noise
- scatterplot(Rx_symbols)
- 802.11 Tx lines of code
 - One single file 52 lines
 - Modulation (3 lines)
 - Spreading (1 line)
- Speed
 - 2 secs for 100 packets
- Find the bug





S/W Demonstration: Build and show



MATLAB Vs C/C++: Spreading and Upsampling C Code

```
Bits spread=addChips(diffOut[slice(i,1)]);
```

```
Bits
IEEE802_11b_Transmitter::addChips(const Bits& input) {
    Bits spreadOut(input.size()*Ns,false);
    for (int i=0;i<input.size();++i) {
        for(int j=0; j<11; ++j) {
            spreadOut[i*Ns+4*j]= m_chip[j]^input[i];
        }
    }
    return spreadOut;</pre>
```

M Code

Tx_chips=reshape(Barker*Tx_symbols',[],1);
Tx_samples(1:Samples_per_chip:end)=Tx_chips;



}



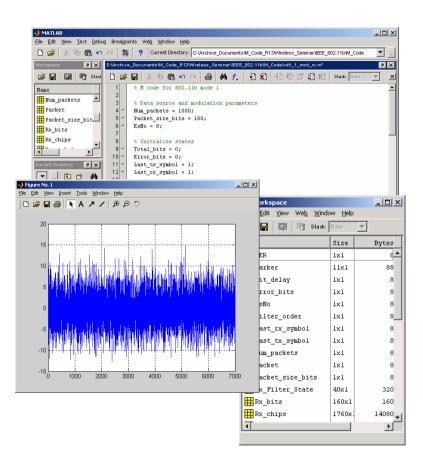
MATLAB Pros and Cons

Pros

- Interactive
- Easy signal visualization
- Canned common functions
- Faster development

Cons

- Limited data types
- Limited low-level control
- Less memory efficient
- Slower to execute for scalars, loops before R13

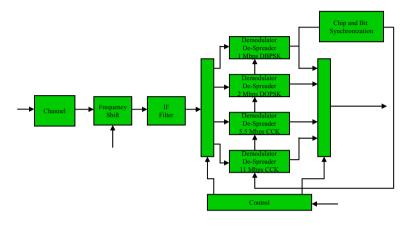






Limitations of C and M for System Design

- No architecture information
 - Can only model a pipeline
 - Can't describe a real system
- No timing information
 - Can only model uniform Fs
 - Difficult to model delays
 - Must manually handle state
 - Can't model A/M-S
 - Difficult to model Rx algorithms





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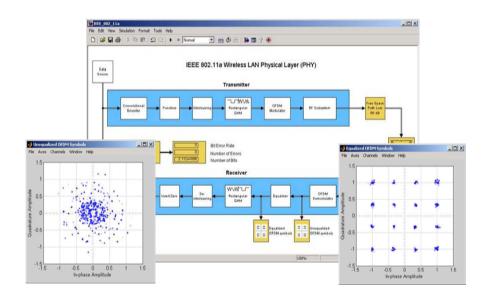






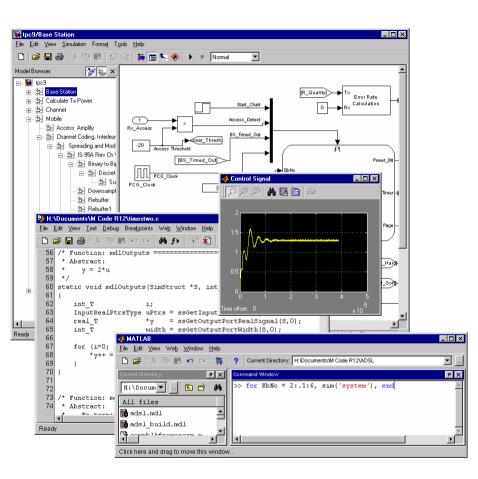


Simulink





Simulink

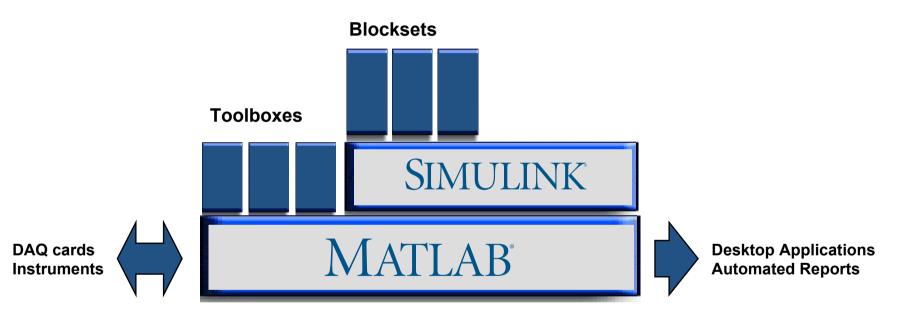


- Hierarchical block diagram design and simulation tool
- Digital, analog/mixed signal and event driven
- Visualize Signals
- Co-develop with C code
- Integrated with MATLAB





Simulink in The MATLAB Environment







The Simulink Block Libraries

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S/W Demonstration: Build

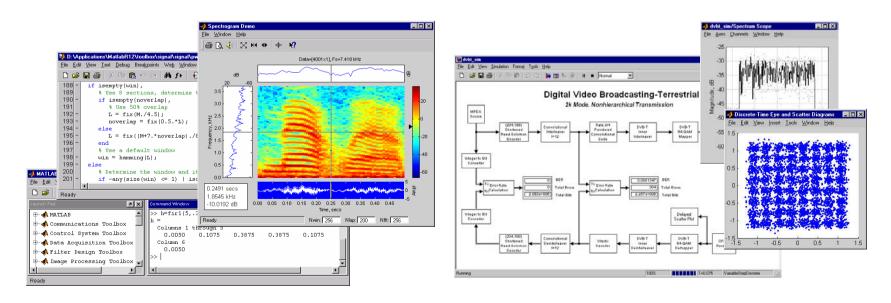


- Simulink
 - Sources and sinks
 - Continuous and Discrete
 - Math, Non-Linear
 - Look-up tables, user functions
 - Subsystems, verification
- DSP Blockset
 - Sub libraries
- Communications Blockset
 - Sub libraries
- Fixed-Point Blockset
- Power-Systems Blockset
- Incremental development



The MathWorks products for DSP and Communications

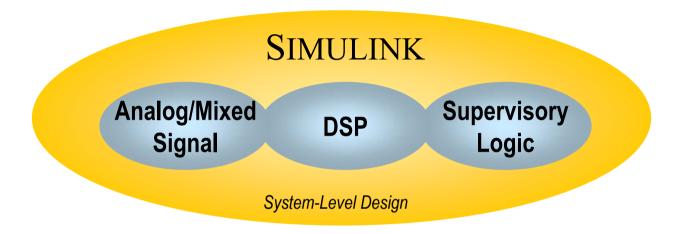
- Accelerating engineering design and discovery
- MATLAB for algorithm development and analysis
- Simulink for system-level design







MathWorks Integrated Design Solution

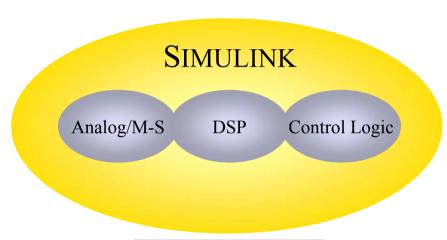


Common tool for all design teams Simulate component interactions Test behavior of whole system No re-design necessary





Modeling system components



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Analog/Mixed-Signal

- E.g. PLLs, data converters
- Continuous time, variablestep ODE solvers

DSP

- E.g. Baseband processing, speech processing
- Discrete time, fast framebased processing. Bit-true cycle accurate.

Control Logic

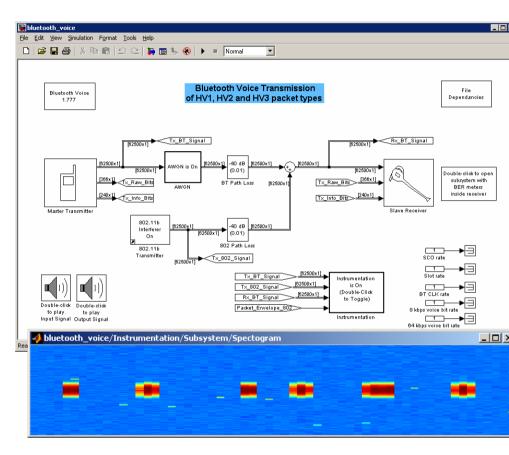
- E.g. MAC layer, acknowledgement schemes
- Reactive or event driven state machines





End-to-end systems

- Digital and analog operations such as coding, interleaving and modulation
- Channel models, error coding, sources, sinks
- Multiple rates for frames, symbols, bit and sample rates
- Synchronization
- Performance testing
- Analog, digital, hybrid, and event-driven simulation







Co-develop with C Code

Simulink Lib	prary Browser	
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	definable block. Blocks may be written in M, C, Fortran or Ada and	
must conform to S-f	function standards. t.x.u and flag are automatically passed to the S-	
function by Simulink parameters' field.	K. "Extra" parameters may be specified in the 'S-function	
parameters noia.		
🖃 🙀 Simulink		
	S-Function Builder: dmt/S-Function Builder1	_
🖄 Functio	S-function name: mod3 Bui	
- 🖄 Math	S-function name. Jmod3Bui	lia
🖄 Nonline	S-function parameters: length(b),b	
- 🖄 Signals		
🖄 Sinks	1. Initialization 2. Libraries 3. Outputs 4. Continuous Derivatives 5. Discrete Update 6. Build In	nto
- 🗠 Source		
🔤 🔤 Subsys	Enter your C-code or call your algorithm. The inputs and outputs of the S-function must be of type doubl referenced as u[0], u[1], etc and v[0], v[1], etc. respectively. S-functions parameters are of type double an	
🛨 🔙 CDMA Refe		
🗄 🐻 🔂 Communica	xD[0]xD[n], xC[0]xC[n], u_width and y_width respectively.	
🙀 Control Sys	Code for the mdlOutputs function	
🖅 🙀 DSP Block:	int bit, real_bits, imag_bits, channel, num_channel_bits, index=0;	
🖅 🔙 Developer's	float sum; bool even num bits;	
🕂 🙀 Dials & Gau	bool even_num_bits;	
🗄 🙀 Fixed-Point	for (channel=0;channel <param0[0];channel++)(< td=""><td></td></param0[0];channel++)(<>	
🗄 🕞 Fuzzy Logic	even num hits=(floor(num channel hits/2,0)==(num channel hits/	12.
MPC Block		
🛨 🔤 Motorola D	And American strategies of	1
🗄 🔂 NCD Block	real bits=num channel bits/2;	
🗄 🔤 Neural Nett	imag_bits=num_channel_bits/2;	
🛨 🙀 Power Syst		
🙀 Real-Time \	real bits=(num channel bits+1)/2;	
🗄 🔂 Real-Time \	mag_breb (man_channer_breb 1)/2,	
🔙 Report Ger		14
🗄 🙀 S-function (ЪÊ
}eady		_
	Inputs are needed in the output function(direct feedthrough)	
	Cancel	Help

S-function block in Simulink

- API to specify outputs, state, parameters and sample-times
- S-function builder in Simulink
 - GUI to enter C Code
 - Predefined variables for input, output and states





Fixed Point Simulation

- New integrated fixed point in core Simulink (R13)
- User-definable data types
- Analysis tools
 - log min, max, overflows block-by-block
- Floating point override options

ixed-Point Settings - untitled2 III =
III III IIII IIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIII
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Links to implementation

Real-Time Workshop

- Automatically generates ANSI C from Simulink
- Customizable code
- Rapid Prototyping
- Embedded Targets
 - TI C6000
 - Motorola MPC555

Altera DSP Builder

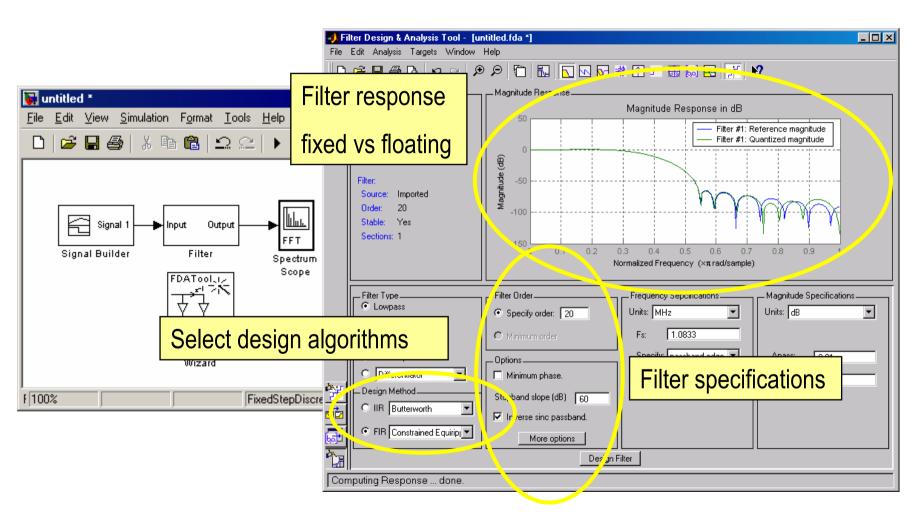
- Bit-true and cycle-true Simulink library for common functions
- Automatic HDL code generation from a Simulink model
- Available from Altera







FIR Filter Design: demo





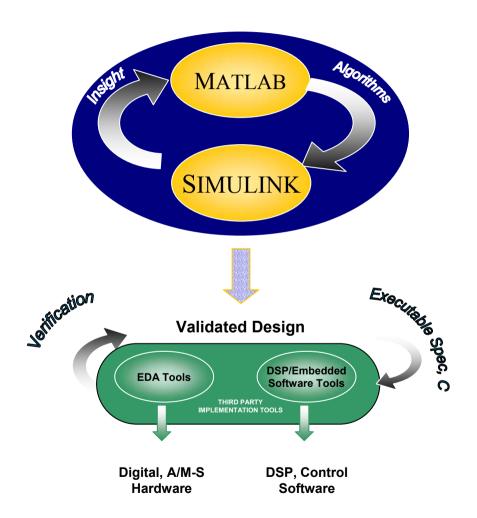




Summary



MATLAB and Simulink



- Create validated design
- Use as reference or executable specification to test low-level designs against
- Provide clear specifications
- Detect design flaws early
- Reduce risk and time-tomarket





Further Information on Products and Services

- Product information and animated demonstrations
 - www.mathworks.com/products/dsp_comm
- Events
 - www.mathworks.com/dsp_events
 - Regular on-line software demonstrations

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MATLAB Central

www.mathworks.com/matlabcentralMathWorks and user contributed models

